

Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS



Motor type : 1AV3162A

INNOMOTICS XP - 160 M - IM B3 - 2p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks II 3D Ex tc IIIB T 120°C Dc

Electrical data

-/-

U	Δ / Y	f	P	P	I	n	M	η ³⁾			cosφ ³⁾			I _A /I _N	M _A /M _N	M _K /M _N	IE-CL
[V]		[Hz]	[kW]	[hp]	[A]	[1/min]	[Nm]	4/4	3/4	2/4	4/4	3/4	2/4	I _I /I _N	T _I /T _N	T _B /T _N	
DOL duty (S1) - 155(F) to 130(B)																	
400	Δ	50	11.00	-/-	19.60	2945	35.5	91.2	91.4	90.6	0.89	0.86	0.79	8.3	2.5	3.5	IE3
690	Y	50	11.00	-/-	11.30	2945	35.5	91.2	91.4	90.6	0.89	0.86	0.79	8.3	2.5	3.5	IE3
460	Δ	60	12.60	-/-	19.30	3540	34.0	91.0	90.9	89.5	0.90	0.87	0.81	8.4	2.5	3.5	IE3
460	Δ	60	11.00	-/-	17.20	3555	29.5	91.0	90.4	88.4	0.88	0.85	0.77	9.5	2.9	4.0	IE3
IM B3 / IM 1001		FS 160 M				IP55			IEC/EN 60034		IEC, DIN, ISO, VDE, EN						
Environmental conditions : -20 °C - +40 °C / 1000 m									Locked rotor time (hot / cold) : 21.3 s 29.7 s								

Mechanical data


Sound level (SPL / SWL) at 50Hz 60Hz	77 / 85 dB(A) ^{2) 3)}	82 / 90 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0370 kg m ²		Thermal class	F
Bearing DE NDE	6209 2Z C3	6209 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L _{10mh} F _{Rad min} for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Frame material	aluminum
Regreasing device	Without		Net weight of the motor (IM B3)	75 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Locating bearing NDE		Color, paint shade	RAL7030
Condensate drainage holes	Without		Motor protection	(B) 3 PTC thermistors - for tripping (2 terminals)
External earthing terminal	With (standard)		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box

Terminal box position	top	Max. cross-sectional area	16 mm ²
Material of terminal box	Aluminium	Cable diameter from ... to ...	19 mm - 28 mm
Type of terminal box	TB1 J00	Cable entry	2xM40x1,5-2xM16x1,5
Contact screw thread	M5		

I_A/I_N = locked rotor current / current nominal
M_K/M_N = locked rotor torque / torque nominal
M_B/M_N = break down torque / nominal torque
1) L_{10mh} according to DIN ISO 281 10/2010
2) at rated power I at full load
3) Value is valid only for DOL operation with motor design IC411

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Responsible department IN LVM	Technical reference	Created by SPC	Approved by Created automatically	Technical data are subject to change! There may be discrepancies between calculated and rating plate values.		Link documents	
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